## **CLAIMS**

- 1. An injection system for injecting fluid into a patient, the injection system comprising:
  - a fluid delivery apparatus;
- a fluid path structured to be disposed between the fluid delivery apparatus and the patient;
- a control unit in communication with and operable to control the fluid delivery apparatus; and
- a control mechanism in communication with the control unit and in fluid communication with the fluid path, the control mechanism comprising a sensor that generates and sends a signal to the control unit,

whereby the control unit controls the injection of fluid into the patient in proportion to the signal.

- 2. The injection system of Claim 1 wherein the control mechanism is hand-operated.
- 3. The injection system of Claim 1 wherein the control mechanism further comprises an actuator mechanism in communication with the sensor.
- 4. The injection system of Claim 3 wherein the sensor senses movement of the actuator mechanism by an operator.
- 5. The injection system of Claim 4 wherein the signal generated by the sensor is proportional to the movement of the actuator mechanism.
- 6. The injection system of Claim 3 wherein the actuator mechanism comprises a plunger.
  - 7. The injection system of Claim 1 wherein the sensor comprises a potentiometer.
- 8. The injection system of Claim 3 wherein the flow rate of the fluid is controlled by the control unit.

- 9. The injection system of Claim 1 wherein the control mechanism is reusable.
- 10. The injection system of Claim 4 wherein the volume of injected fluid is proportional to the displacement of the actuator mechanism.
- 11. The injection system of Claim 4 wherein the flow rate of injected fluid is proportional to the rate of displacement of the actuator mechanism.
- 12. The injection system of Claim 4 wherein the flow rate of injected fluid is proportional to the displacement of the actuator mechanism.
- 13. The injection system of Claim 1 wherein the proportional relationship between the signal and the injection of fluid is a substantially linear relationship.
- 14. The injection system of Claim 1 wherein the pressure generated by the fluid in the fluid path is communicated to the control mechanism.
- 15. The injection system of Claim 1, further comprising a manifold disposed in the fluid path between the fluid delivery apparatus and the patient.
- 16. The injection system of Claim 15 wherein the control unit is in communication with and is operable to control the manifold.
  - 17. The injection system of Claim 15 wherein the manifold is manually operated.
  - 18. The injection system of Claim 15 wherein the manifold is power activated.
- 19. The injection system of Claim 1, wherein the sensor is an integrated element of the control mechanism.
- 20. The injection system of Claim 1, wherein the control mechanism further comprises a tactile feedback control unit.
- 21. The injection system of Claim 1, wherein the control mechanism further comprises a syringe and the sensor is formed on a cradle coupled to the syringe.